

# QoS Provisioning in Industrial Wireless Sensor Networks

Samuele Zoppi, H. Murat Gürsu, Wolfgang Kellerer

Chair of Communication Networks
Technical University of Munich, Germany





ШП

Next-generation industrial automation systems will be **wirelessly** interconnected [HPO16].



Samuele Zoppi | ITG Fachausschuss 5.2 workshop on "Cellular Internet of Things" | Munich, Germany

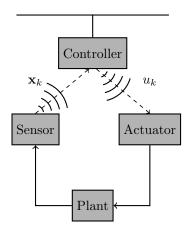


Next-generation industrial automation systems will be wirelessly interconnected [HPO16].

Networked Control Systems (NCS): control loops closed over the network.



Industrial NCS.





Next-generation industrial automation systems will be **wirelessly** interconnected [HPO16].

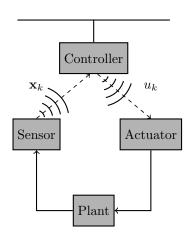
Networked Control Systems (NCS): control loops *closed* over the network.

Stochastic LTI control system:

$$\mathbf{x}_{k+1} = \mathbf{A}\mathbf{x}_k + \mathbf{B}u_k + \mathbf{w}_k,$$
 $u_k = -\mathbf{K}\mathbf{x}_k,$ 

 $\mathbf{x}_k$  plant dynamic,  $u_k$  control law.







Next-generation industrial automation systems will be **wirelessly** interconnected [HPO16].

Networked Control Systems (NCS): control loops *closed* over the network.

Stochastic LTI control system:

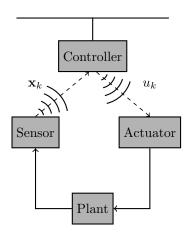
$$\mathbf{x}_{k+1} = \mathbf{A}\mathbf{x}_k + \mathbf{B}u_k + \mathbf{w}_k,$$
 $u_k = -\mathbf{K}\mathbf{x}_k,$ 

 $\mathbf{x}_k$  plant dynamic,  $u_k$  control law.

Sensor sends  $\mathbf{x}_k$  to the Controller.

Controller computes and sends  $u_k$  to the Actuator.

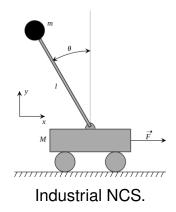


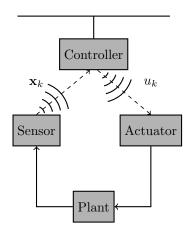




ШП

Inverted pendulum as benchmark NCS application.





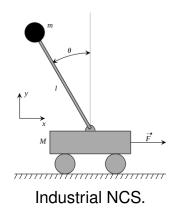


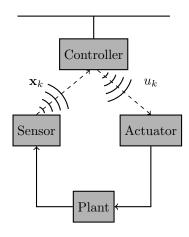
### Ш

### Background (2)

Inverted pendulum as benchmark NCS application.

Sampling frequency: 20 Hz.







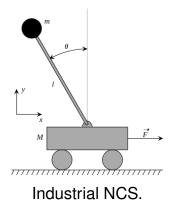
ТШ

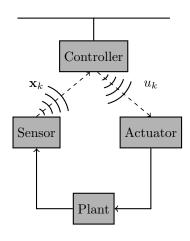
Inverted pendulum as benchmark NCS application.

Sampling frequency: 20 Hz.

Uplink traffic:

$$\mathbf{x}_k = \begin{bmatrix} x_k \\ \dot{x}_k \\ \theta_k \\ \dot{\theta}_k \end{bmatrix} \rightarrow 256 \text{ bits @ 20Hz = 5 kbps.}$$







Inverted pendulum as benchmark NCS application.

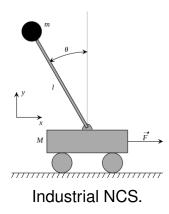
Sampling frequency: 20 Hz.

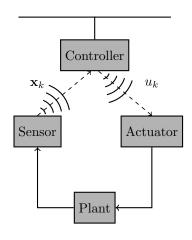
Uplink traffic:

$$\mathbf{x}_k = \begin{bmatrix} x_k \\ \dot{x}_k \\ \theta_k \\ \dot{\theta}_k \end{bmatrix} \rightarrow 256 \text{ bits @ 20Hz = 5 kbps.}$$



$$u \rightarrow$$
 64 bits @ 20Hz = 1.25 kbps.







Inverted pendulum as benchmark NCS application.

Sampling frequency: 20 Hz.

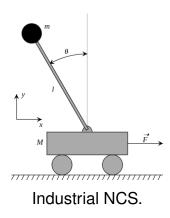
Uplink traffic:

$$\mathbf{x}_k = \begin{bmatrix} x_k \\ \dot{x}_k \\ \theta_k \\ \dot{\theta}_k \end{bmatrix} \rightarrow 256 \text{ bits @ 20Hz = 5 kbps.}$$



$$u \rightarrow$$
 64 bits @ 20Hz = 1.25 kbps.

WSN (PHY IEEE 802.15.4) link  $\rightarrow$  250 kbps.



 $\mathbf{x}_k$ Controller  $\mathbf{x}_k$ Sensor
Actuator





Wireless Sensor Networks (WSN) can support NCS traffic.





Wireless Sensor Networks (WSN) can support NCS traffic.

Control loops pose strict **QoS requirements** on wireless communications.





Wireless Sensor Networks (WSN) can support NCS traffic.

Control loops pose strict **QoS requirements** on wireless communications.

WSN suffers from external interference and unreliable links [GVZK16].





Wireless Sensor Networks (WSN) can support NCS traffic.

Control loops pose strict **QoS requirements** on wireless communications.

WSN suffers from external interference and unreliable links [GVZK16].

Problem: Current WSN lack dynamic real-time QoS provisioning.



Wireless Sensor Networks (WSN) can support NCS traffic.

Control loops pose strict **QoS requirements** on wireless communications.

WSN suffers from external interference and unreliable links [GVZK16].

Problem: Current WSN lack dynamic real-time QoS provisioning.

#### Approach:

- 1. Definition of a QoS provisioning framework for IWSN.
- 2. Implementation of the framework in a testbed.



#### Outline

Background & Motivation

QoS Provisioning Framework

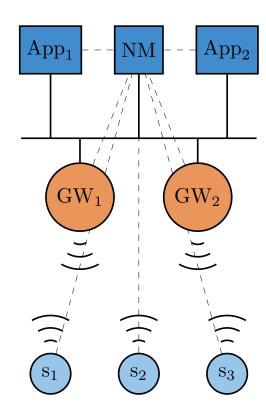
**Implementation** 

Conclusions & Further Work



#### **Network Architecture**

Centralized, star topology.



Network architecture.

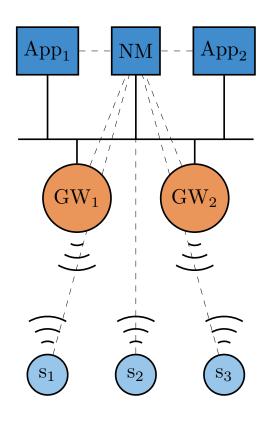


#### **Network Architecture**

Centralized, star topology.

#### Network elements:

- 1. Application (App): industrial NCS application
- Network Manager (NM): manager of the Network Resources of the entire WSN
- 3. **Gateway (GW)**: interface btw the WSN devices, the NM and Apps
- 4. Sensor (s): WSN device



Network architecture.



#### **Network Architecture**

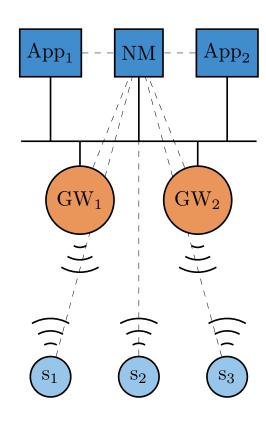
Centralized, star topology.

#### Network elements:

- 1. Application (App): industrial NCS application
- 2. **Network Manager (NM)**: manager of the Network Resources of the entire WSN
- 3. **Gateway (GW)**: interface btw the WSN devices, the NM and Apps
- 4. Sensor (s): WSN device

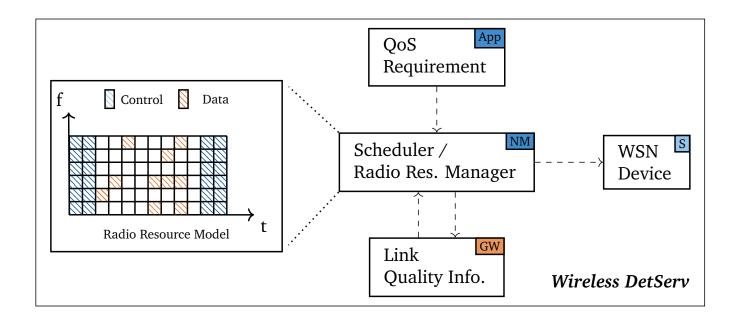
Data links btw NM and WSN devices through the GW.

Control links btw App and WSN devices through the GW.

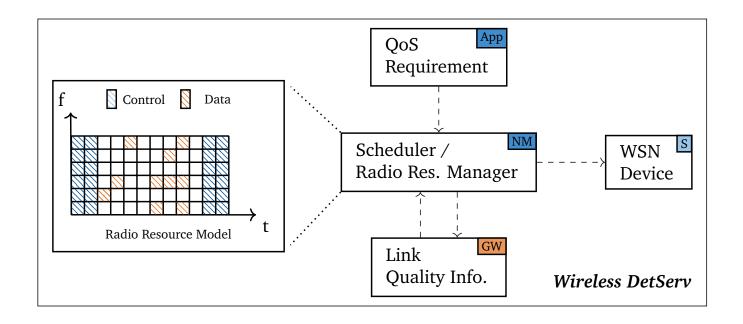


Network architecture.





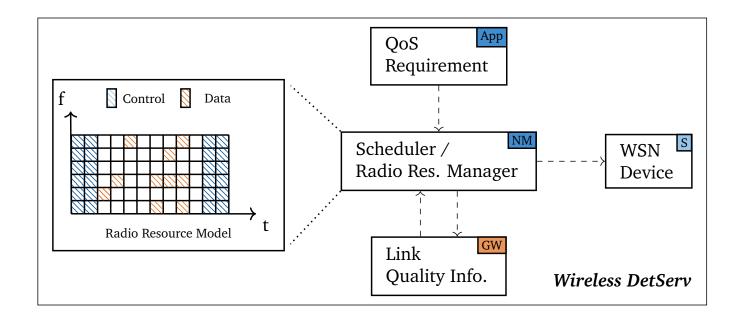




#### Radio Resource Manager inputs:

- 1. QoS requirements from the application.
- 2. QoS Model of the MAC radio resources.
- 3. Link Quality Information of the radio resources.





#### Radio Resource Manager inputs:

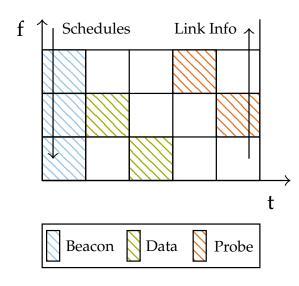
- 1. QoS requirements from the application.
- 2. QoS Model of the MAC radio resources.
- 3. Link Quality Information of the radio resources.

#### Radio Resource Manager outputs:

- 1. Radio resources for Data packets (application).
- 2. Radio resources for Control packets (schedules, LQI probes, ...).



Dynamic scheduling is possible in a TDMA-FDMA radio resource grid model.

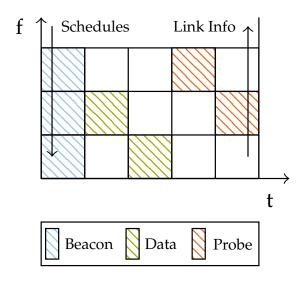




Dynamic scheduling is possible in a TDMA-FDMA radio resource grid model.

#### Dynamic scheduling protocol:

- 1. Acquisition of Link Quality Information (input)
  - → estimated Packet Delivery Ratio
  - → EWMA for estimation

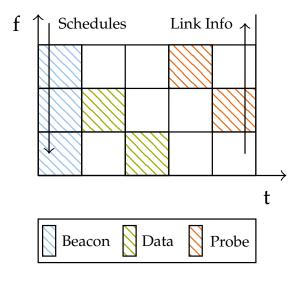




Dynamic scheduling is possible in a TDMA-FDMA radio resource grid model.

#### Dynamic scheduling protocol:

- 1. Acquisition of Link Quality Information (input)
  - → estimated Packet Delivery Ratio
  - → EWMA for estimation
- 2. Acquisition of QoS requirements (input)
  - → Target application reliability (i.e. 90%)
  - → Target delay bound (deadline)

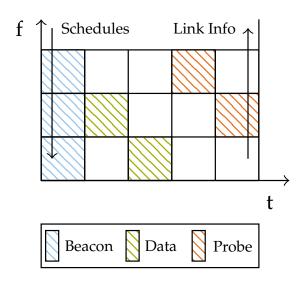




Dynamic scheduling is possible in a TDMA-FDMA radio resource grid model.

#### Dynamic scheduling protocol:

- 1. Acquisition of Link Quality Information (input)
  - → estimated Packet Delivery Ratio
  - → EWMA for estimation
- 2. Acquisition of QoS requirements (input)
  - → Target application reliability (i.e. 90%)
  - → Target delay bound (deadline)
- 3. Distribution of new schedules (output)
  - → sequence of radio resources (time-freq. pairs)
  - $\rightarrow$  distributed using the beacon
  - → calculated with a **reliability-based scheduler**





# QoS Framework (3) - Scheduling algorithm

Reliability is provided allocating multiple transmissions in the frame.

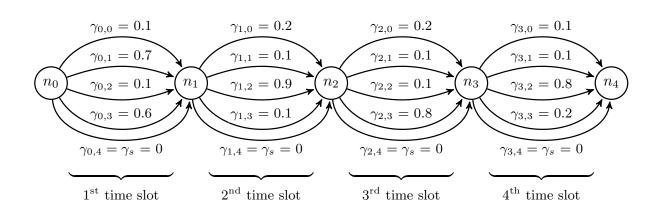


# QoS Framework (3) - Scheduling algorithm

Reliability is provided allocating multiple transmissions in the frame.

The radio resources are modeled using a **scheduling graph**:

- Nodes represent time instants before/after time slots.
- Edges represent different frequencies and they are weighted by their PDR.





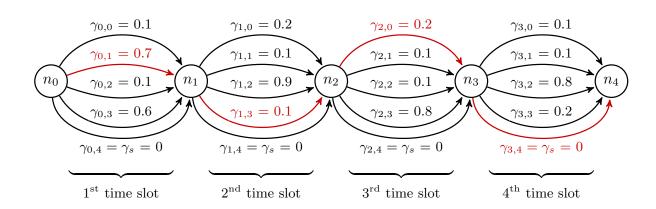
# QoS Framework (3) - Scheduling algorithm

Reliability is provided allocating multiple transmissions in the frame.

The radio resources are modeled using a **scheduling graph**:

- Nodes represent time instants before/after time slots.
- Edges represent different frequencies and they are weighted by their PDR.

A Constrained Shortest Path scheduling algorithm finds the **schedule** (path) fulfilling the **target reliability**.  $\rightarrow \{(0,1),(1,3),(2,0)\}$ 

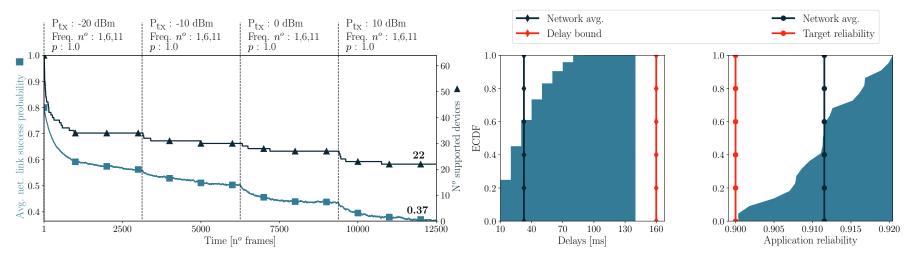




# QoS Framework (4) - Results



Simulation results of dynamic scheduling with latency and reliability constraints.



Reliability-based scheduling [eaED].

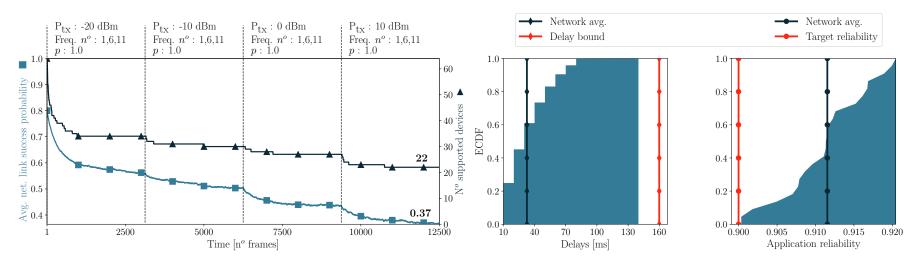




# QoS Framework (4) - Results

Simulation results of dynamic scheduling with latency and reliability constraints.

WSN operating in a dynamic interference scenario (Wi-Fi APs, @2.4GHz).



Reliability-based scheduling [eaED].



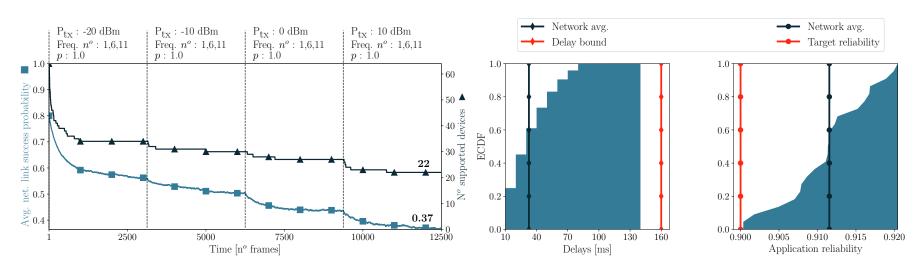
### ТИП

# QoS Framework (4) - Results

Simulation results of dynamic scheduling with latency and reliability constraints.

WSN operating in a dynamic interference scenario (Wi-Fi APs, @2.4GHz).

Dynamic scheduling in presence of increasing Wi-Fi transmission power (Ptx).



Reliability-based scheduling [eaED].

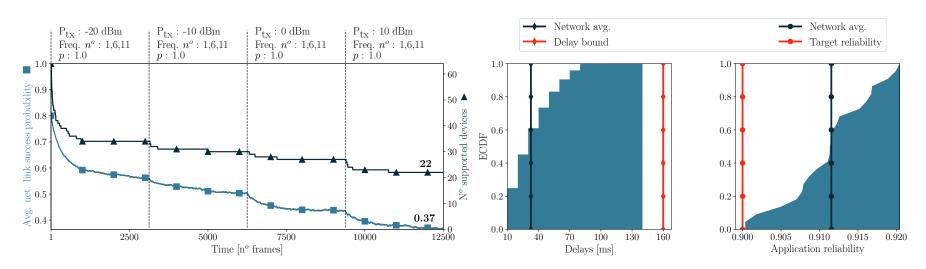


# QoS Framework (4) - Results

Simulation results of dynamic scheduling with latency and reliability constraints.

WSN operating in a dynamic interference scenario (Wi-Fi APs, @2.4GHz).

Dynamic scheduling in presence of increasing Wi-Fi transmission power ( $P_{tx}$ ).



Reliability-based scheduling [eaED].

WDetServ guarantees reliability and delay bounds reacting against interference.



#### Outline

Background & Motivation

QoS Provisioning Framework

Implementation

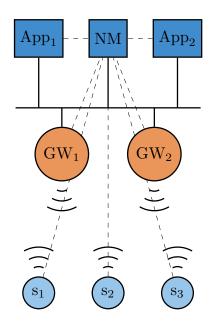
Conclusions & Further Work

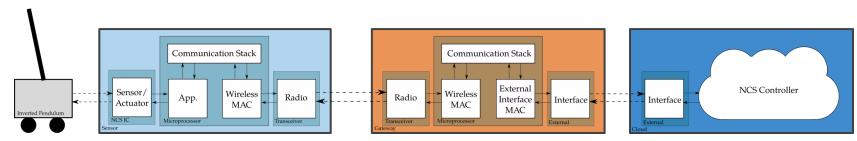


### Implementation (1)

#### Deployment of an WDetServ NCS testbed:

- 1. Control logic (Controller) in the Cloud.
- 2. Sensing and Actuation in the WSN devices.
- 3. Gateway acts as forwarding entity.
- 4. Inverted Pendulum as benchmark control application.



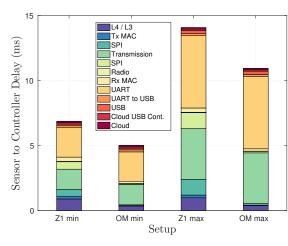




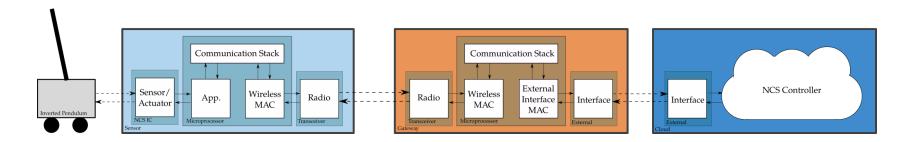
# Implementation (2)

ШП

**Problem:** several HW and SW latency bottlenecks.



Sensor-to-cloud delay measurements[GZO<sup>+</sup>].





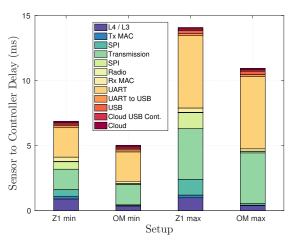
### Implementation (2)

ТИП

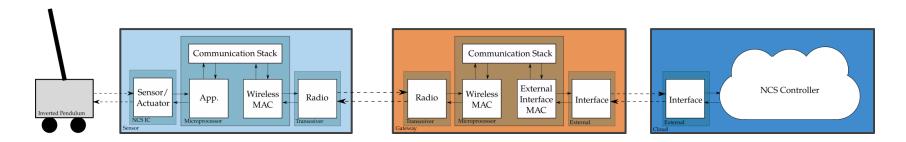
**Problem:** several HW and SW latency bottlenecks.

**Solution:** ad-hoc HW solutions for GW and WSN:

- Gateway
   high perf., multi-radio, multi-processor
   → low-latency, multi-channel SDR
- Sensor limited perf., single antenna, single processor
   → Zolertia Z1/RE-Mote, TI SimpleLink



Sensor-to-cloud delay measurements[GZO<sup>+</sup>].





#### Outline

Background & Motivation

QoS Provisioning Framework

**Implementation** 

Conclusions & Further Work



NCS traffic can be supported by WSN if QoS provisioning is implemented.



ШП

NCS traffic can be supported by WSN if QoS provisioning is implemented.

Wireless DetServ provides the building blocks for **QoS provisioning** (latency, reliability, QoC, ...) in WSN.





NCS traffic can be supported by WSN if QoS provisioning is implemented.

Wireless DetServ provides the building blocks for **QoS provisioning** (latency, reliability, QoC, ...) in WSN.

The implemented reliability-based scheduler is able to react to changes in the wireless environment.





NCS traffic can be supported by WSN if QoS provisioning is implemented.

Wireless DetServ provides the building blocks for **QoS provisioning** (latency, reliability, QoC, ...) in WSN.

The implemented reliability-based scheduler is able to react to changes in the wireless environment.

**Latency** is the major issue for HW implementation (radio, processing, ext. interface).



#### **Further Work**



Measurements of NCS Inverted Pendulum operating over the testbed will be performed.

NCS cross-layer scheduling algorithms will be developed.

Different Link Quality Estimators will be evaluated in the testbed.

Multi-radio, multi-processor, high-speed interface solutions will be implemented.



#### References

- Samuele Zoppi et al. Reliability-based scheduling for delay guarantees in hybrid wired-wireless industrial networks. *IEEE Transactions on Industrial Informatics*, SUMBITTED.
- M. Gürsu, M. Vilgelm, S. Zoppi, and W. Kellerer. Reliable co-existence of 802.15.4e TSCH-based WSN and Wi-Fi in an aircraft cabin. In *2016 IEEE International Conference on Communications Workshops*, pages 663–668, May 2016.
- Halit Murat Gürsu, Samuele Zoppi, Hasan Yagiz Ozkan, Yadhunandana R. K., and Wolfgang Kellerer. Tactile sensor to cloud delay: A hardware and processing perspective. In *IEEE ICC 2018 SAC Symposium Internet of Things Track (ICC'18 SAC-6 IoT)*, SUBMITTED.
- Mario Hermann, Tobias Pentek, and Boris Otto. Design principles for industrie 4.0 scenarios. In *System Sciences (HICSS), 2016 49th Hawaii International Conference on*, pages 3928–3937. IEEE, 2016.