



ECHORING™

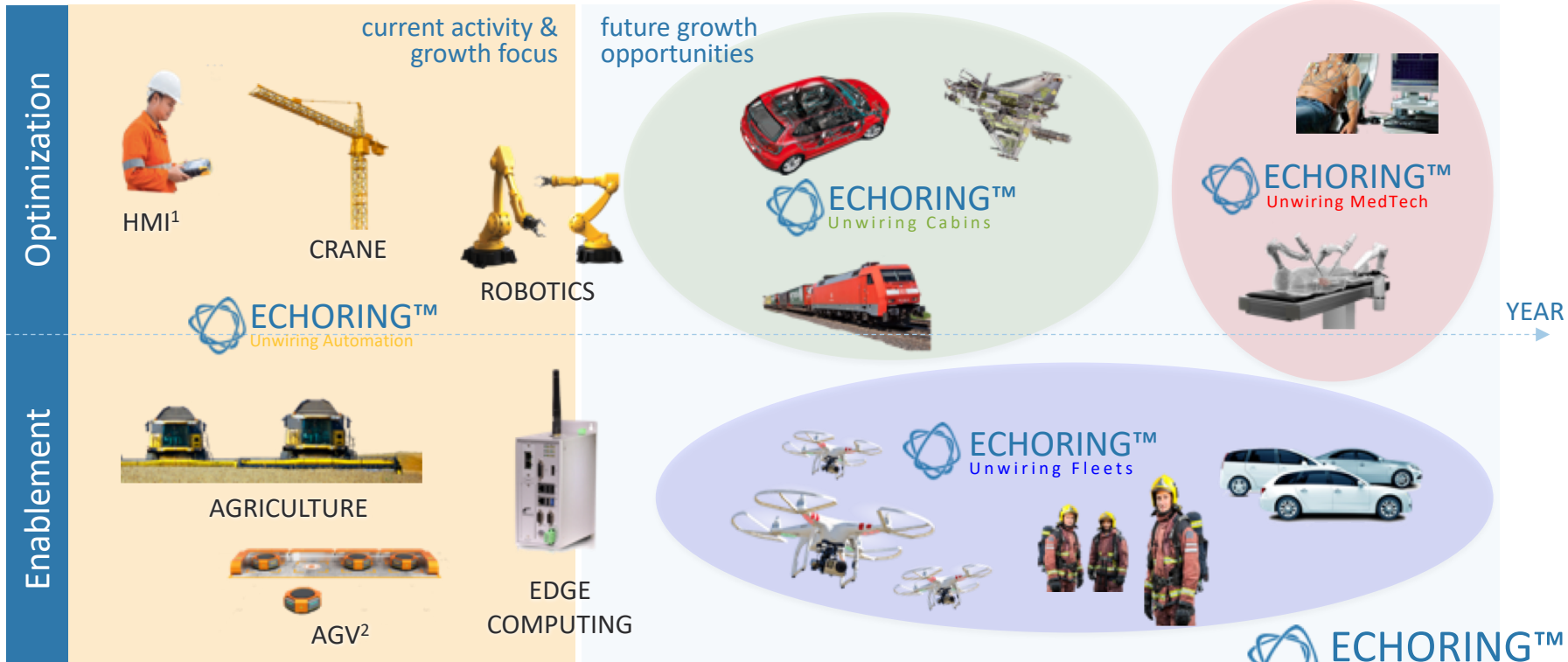
Unwiring Everything

March 15th, 2018 – EchoRing™ Intro
by Jasper Büsch

R3 Communications GmbH

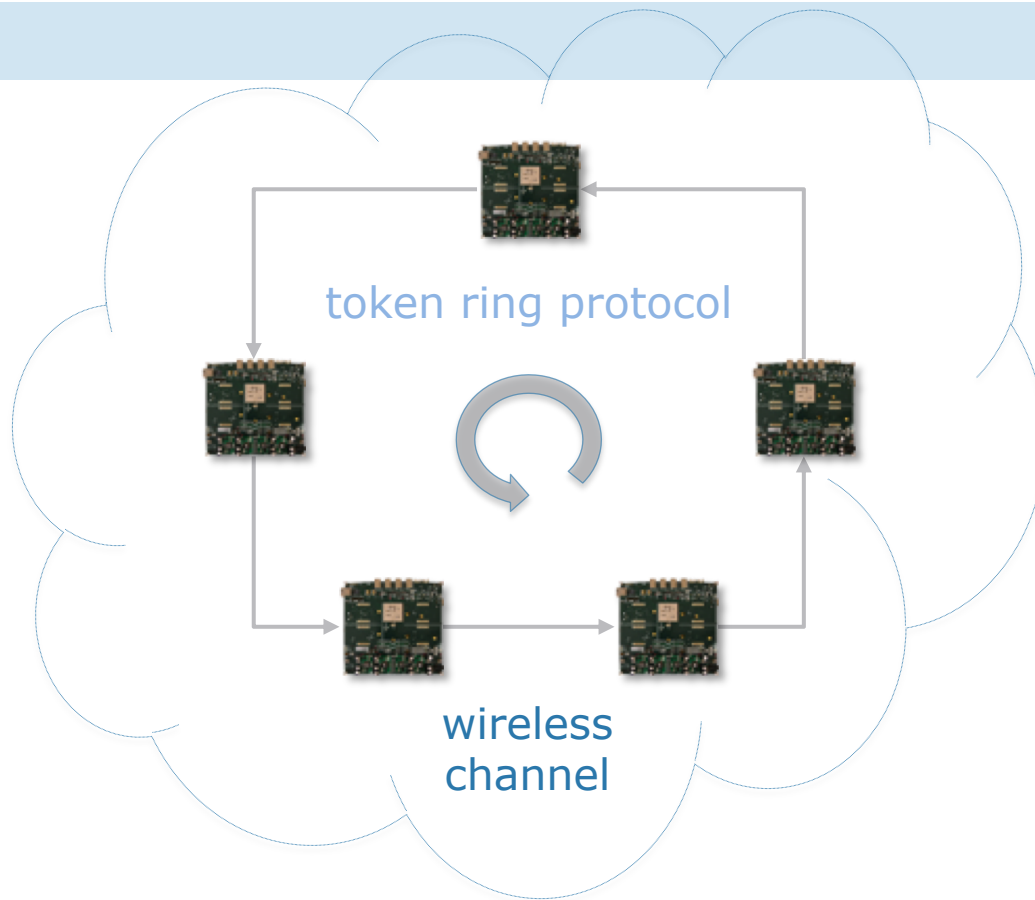


EchoRing™ – in various reliable real-time wireless use cases.





token rotation.

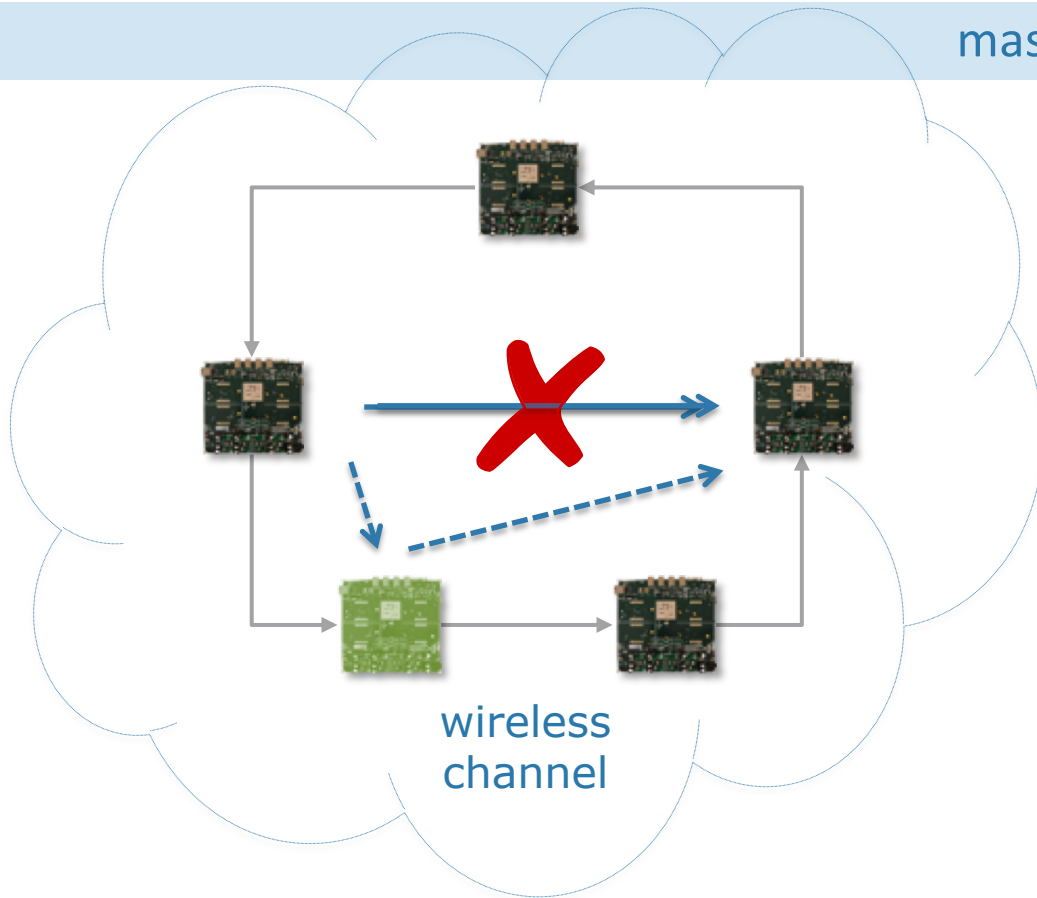




How we improve reliability.



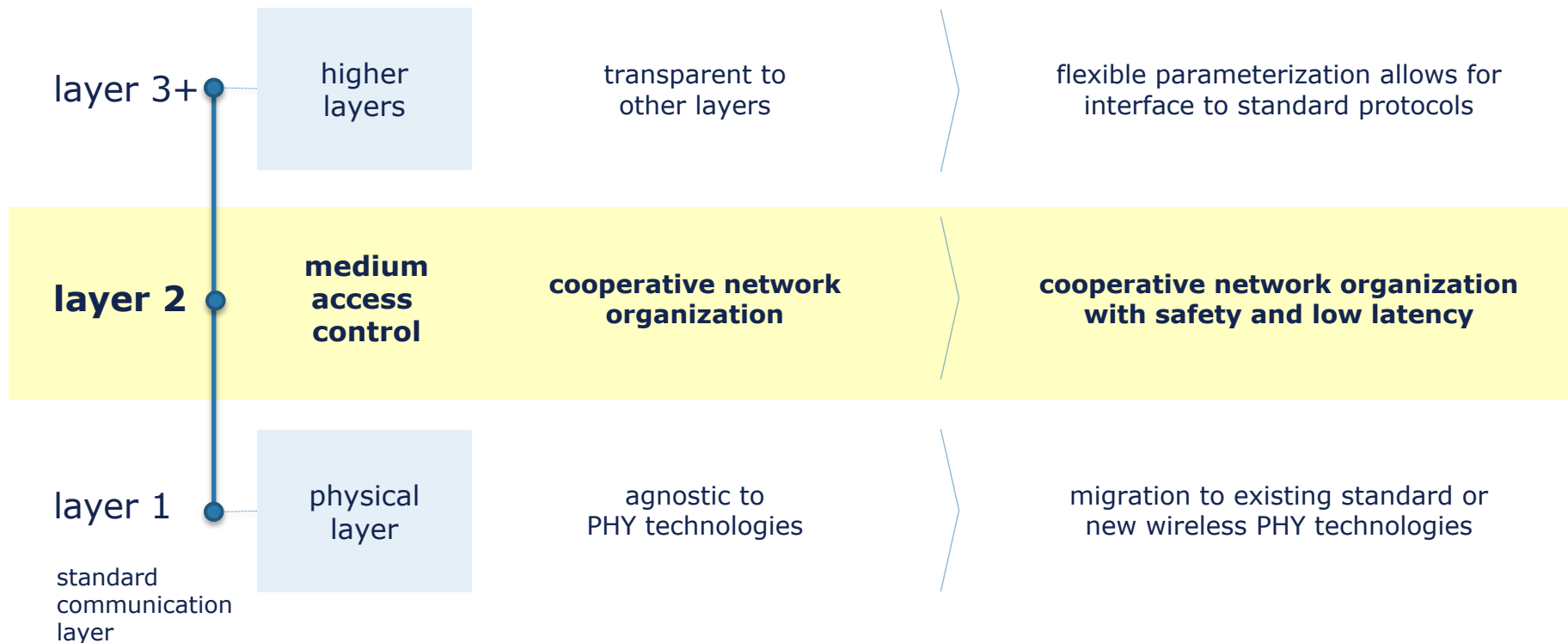
massive cooperation.





Where do we place it?

agnostic to lower layers and transparent to higher layers.

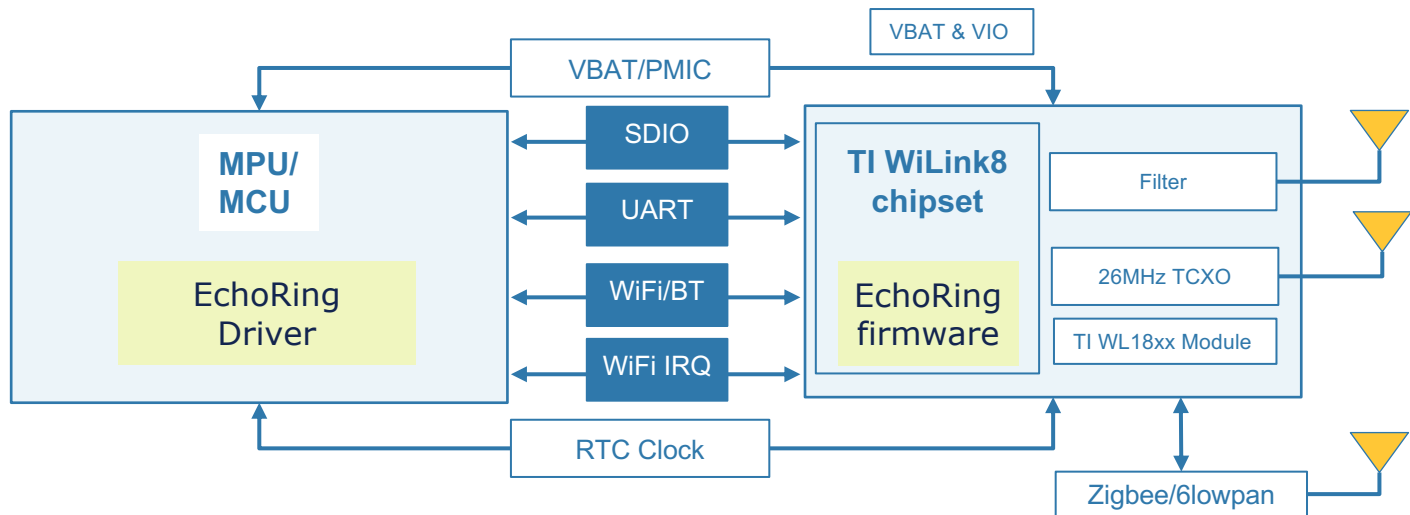




EchoRing™ system block diagram.

driver

firmware



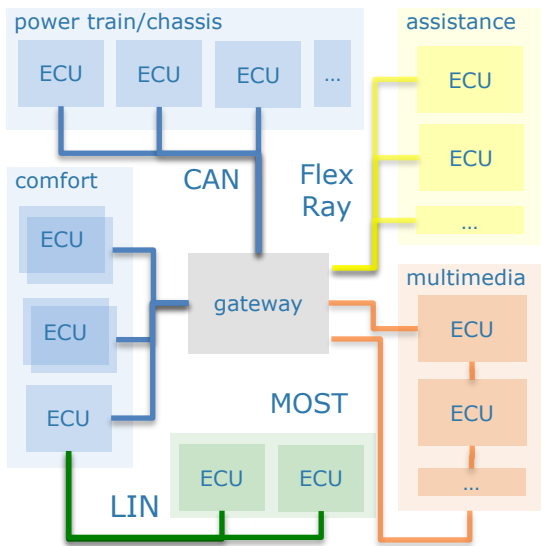
Regular performance

high end performance



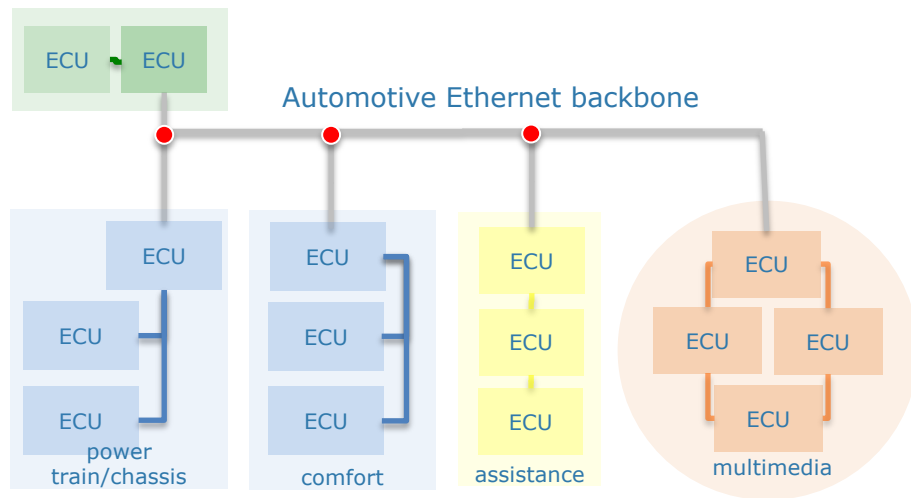
The harness is a car's nervous system...

legacy



gateway approach

modern

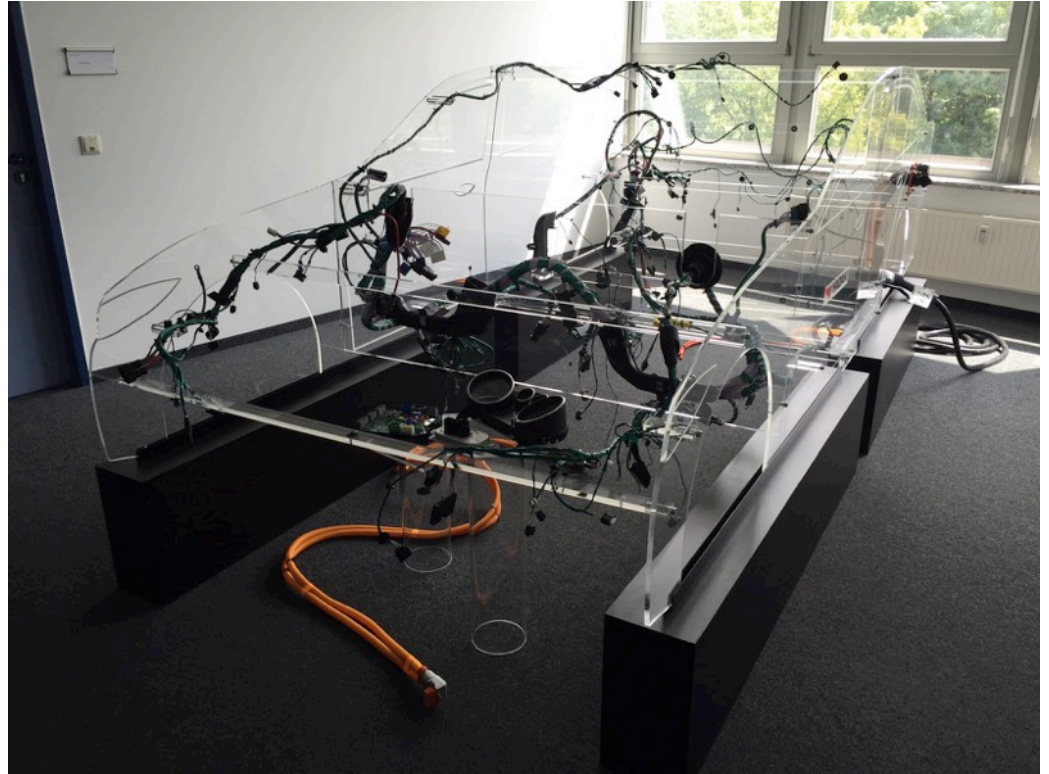
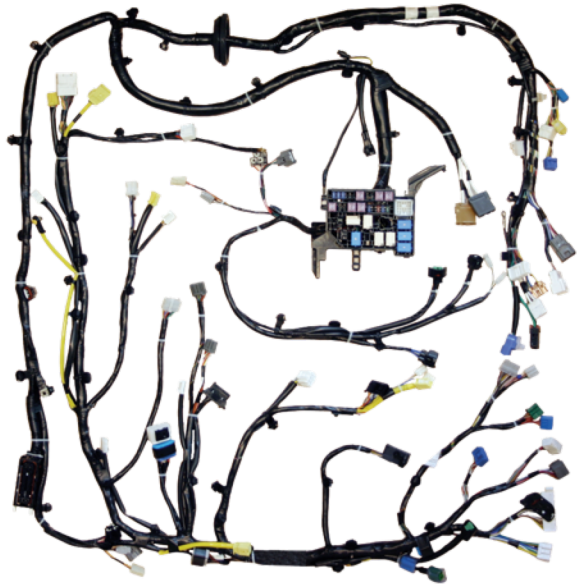


organized domain approach

● Ethernet Switch



..and: a major pain point in automotive.





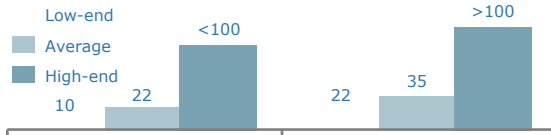
Future trends emphasize problematic tendency.

Expected development car electronics

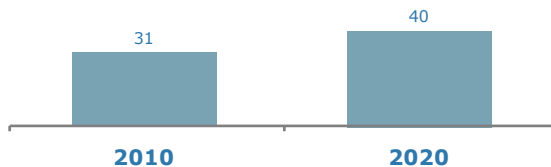
development worldwide intra-vehicle nodes (M#)¹



average electronic controlling units per car (#)¹




cost electronic components per car (%)²




general cost forecast

wireless cost forecast

ECU




- hardware
- integration
- ECU service/repair





- wireless chips
- less variety

HARNESS




- cabling + plugs
- assembly + checks
- integration

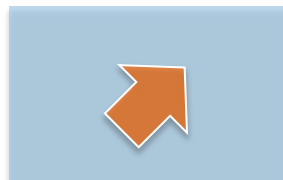




- less cable
- less assembly
- less integration

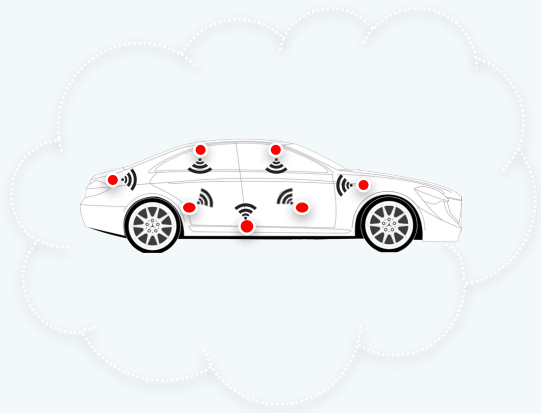
MISC



- total vehicle weight
- architectural flexibility
- quality assurance

- less hardware
- easy add-ons
- easy fault analysis

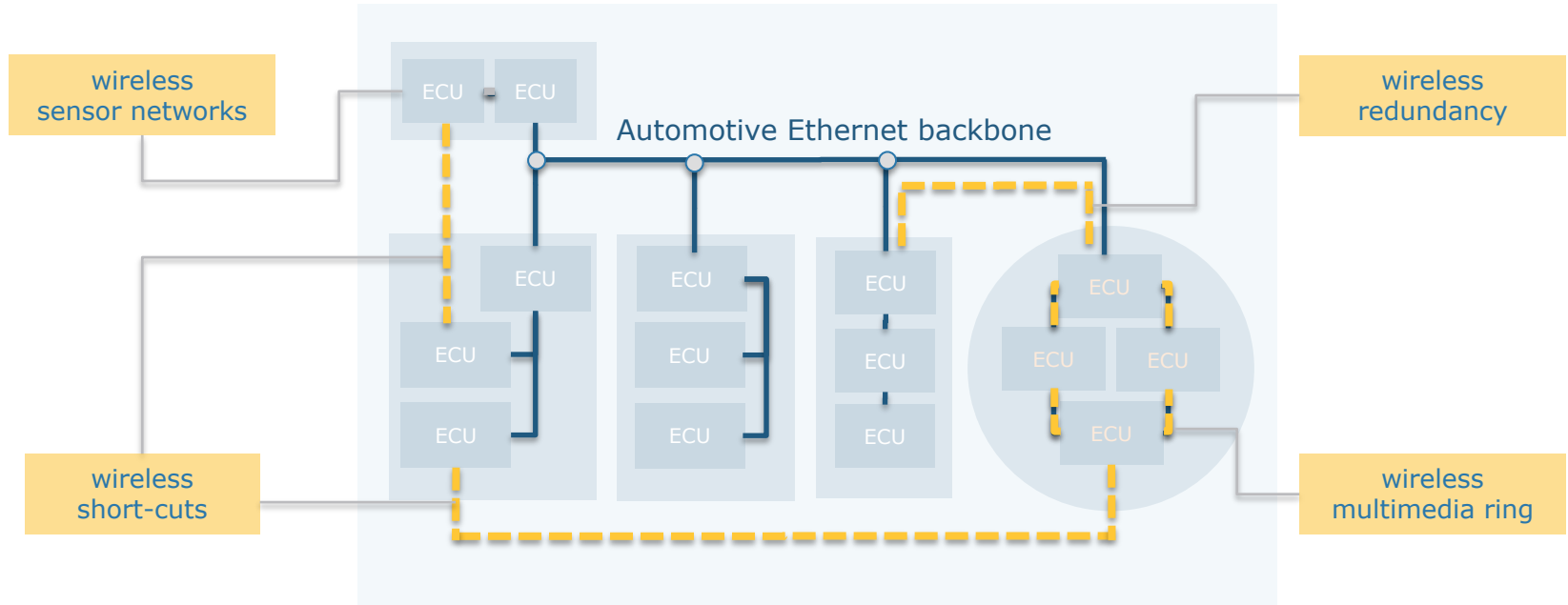


**intra-vehicle
communication
via wireless harness
solution
(e.g. short
cuts/redundancy)**

1. high flexibility and less complexity
2. easy assembly and integration
3. less total cost compared to cable

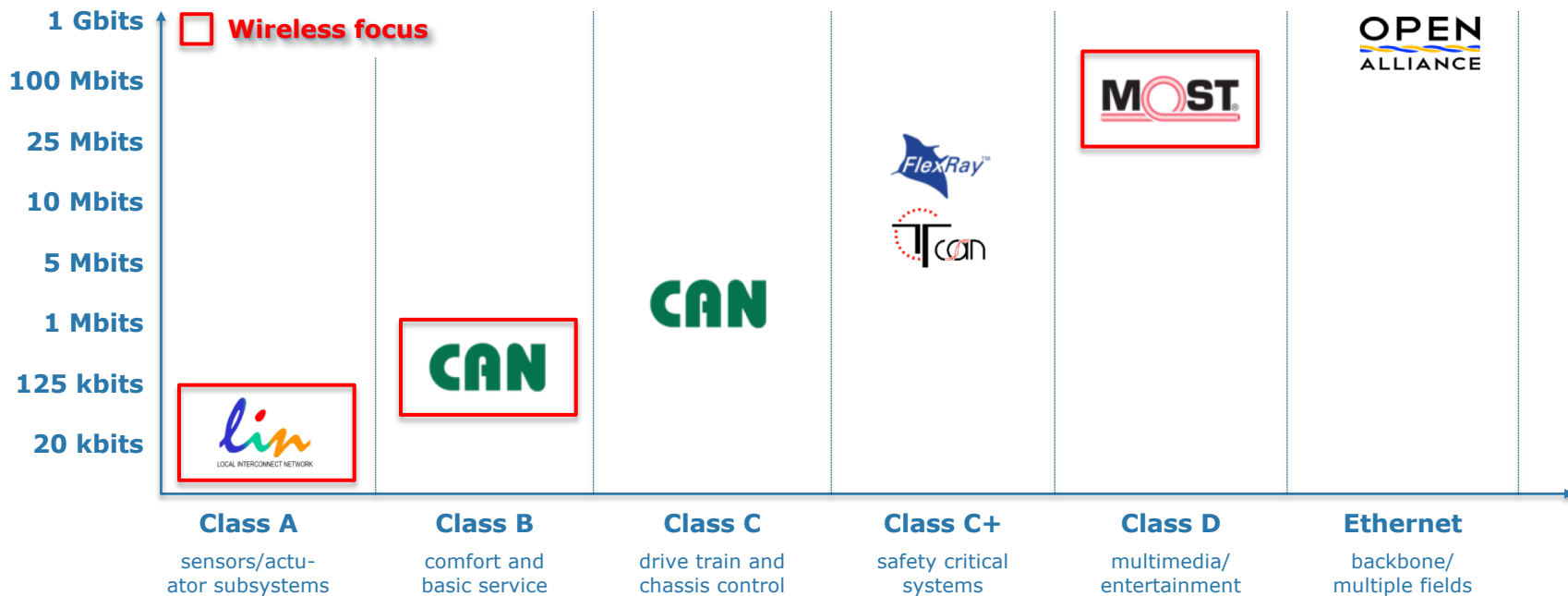


... with different application areas.





Initial application in non-critical systems.





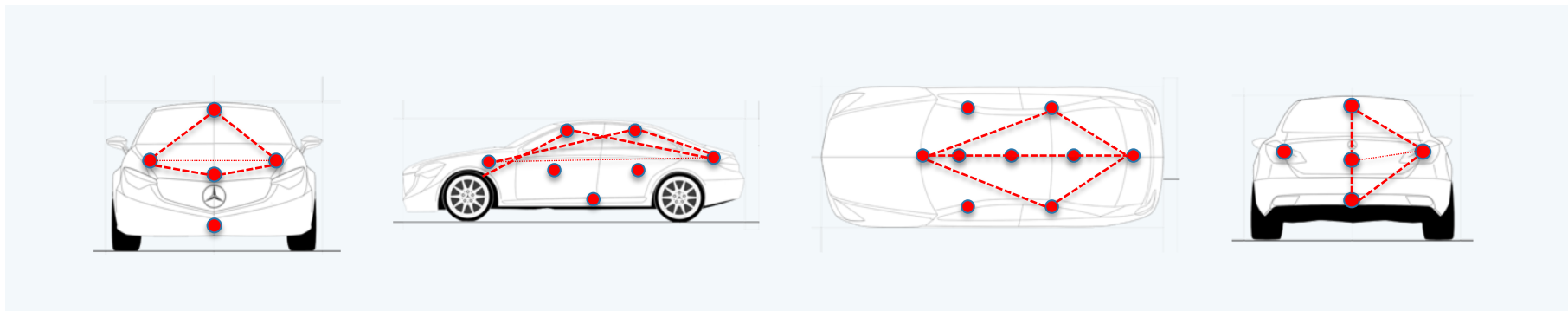
Example – selection of intra-car applications.

front view

side view

top view

rear view



e.g. window regulator transmission

e.g. light control transmission

e.g. rear video signal transmission

e.g. turn signal transmission

● ECU/wireless node direct transmission - - - relay transmission

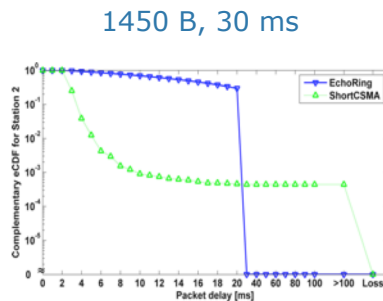
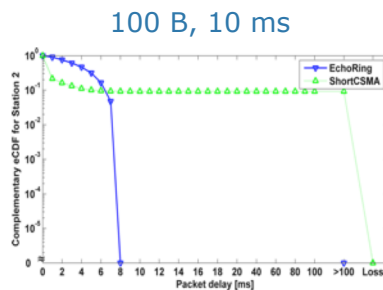


parameter

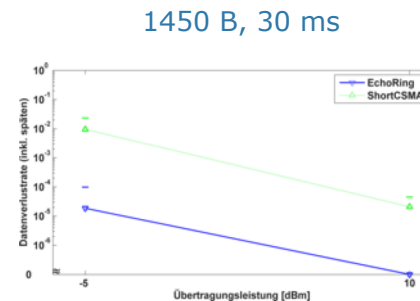
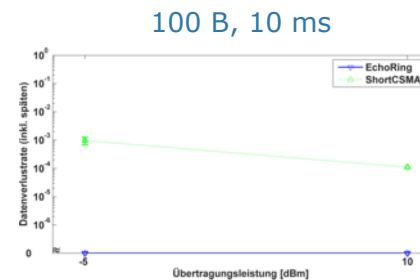
- frequency channel: 5,7 GHz
- transmit power: 0.2-5.0 mW
- payload size: various
- latency: various
- duration: several hours



delay profiles

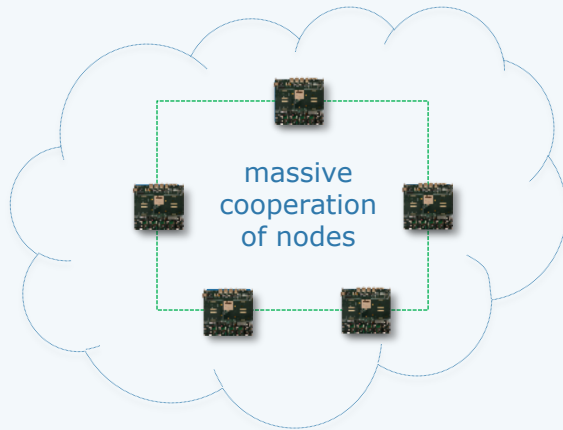


PER results (station 5)





EchoRing™



Logical ring structure
w/ massive cooperation

Wireless Harness

- A Today's harness in cars are not fit for the future

- B Wireless harness extensions good option to overcome problems

- C Wireless systems need high robustness and real-time features

- D Co-existence among wireless systems is a must

- E EchoRing™ has been shown to provide superior performance

- F While being based on COTS hardware and software modifications



THANK YOU!



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Backup Slides



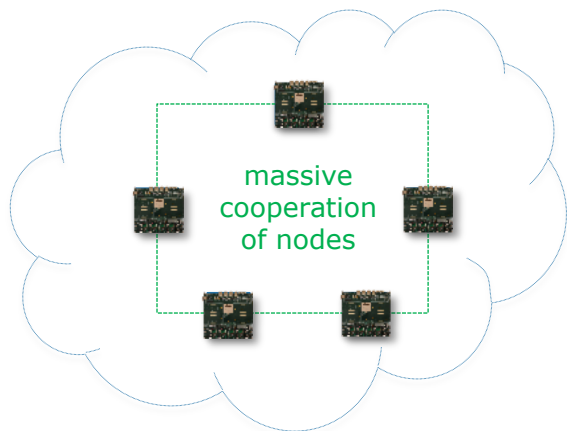
EchoRing specifics in comparison.

	EchoRing					
Area of usage	subnets/soft real-time	subnets	soft real-time	hard real-time	multimedia	multimedia
Application domain	body, chassis, comfort	body	power train, chassis	chassis, power train	multimedia, telem.	Multim., telem., comfort
Transmission	asynchronous	synchronous	asynchronous	(a)synchronous	(a)synchronous	asynchronous
Identification	identifier	identifier	identifier	time slot	-	identifier
Architecture	distributed	single master	multi-master	multi-master	multi-master	distributed
Access control	virtual token ring	polling	CSMA/CA	TDMA	TDMA / CSMA/CA	CSMA/CA, VLAN
Data rate	flexible	20 kbps	1 Mbps	10 Mbps	24 Mbps	100Mbit / 1Gbit
Medium	wireless	single wire	dual-wire	dual-wire/op. fi.	dual-wire/op. fi.	single-twisted-pair
Latency jitter	load dependent	constant	load dependent	constant	data stream	load dependent
Babbling protection	provided	-	not provided	provided	-	-
Extensibility	very high	high	high	low	high	high



Different cooperative systems design available.

basic principle



leveraging instantaneous channel-state knowledge

implementation design

1. EchoRing: Token-based medium access with cooperation
2. synchronous TDMA with decentralized cooperation
3. synchronous TDMA with centralized cooperation

flexible system design for different applications

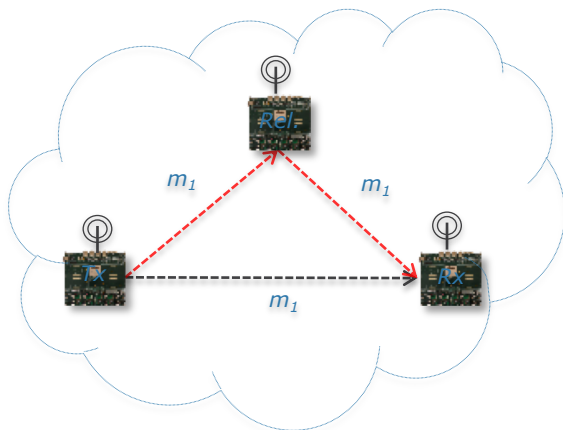
advantages

- extremely high reliability without modifications of the PHY
- software realization on standard COTS transceivers
- potential combination with other reliability enhancing mechanisms

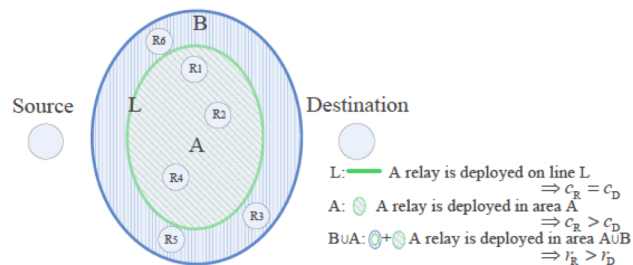
hardware/PHY agnostic technology



system model



research results

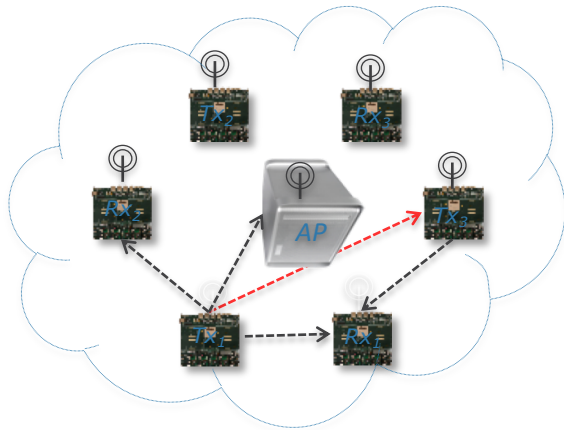


relaying gain: Higher robustness for fixed deadline

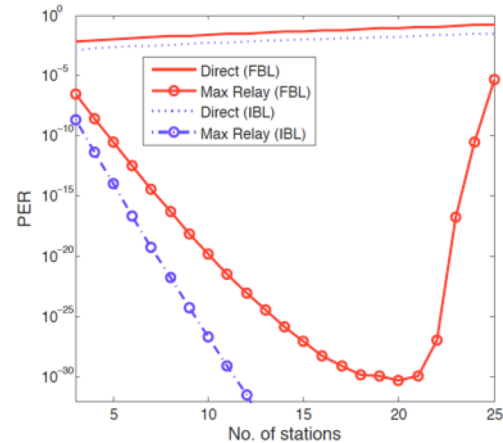
Source: Y. Hu, J. Gross, "On the Performance Advantage of Relaying Under Finite Blocklength Regime" IEEE Comm. Letters, in press, available online



system model



research results



cooperation gain: Higher robustness with higher load at fixed latency

Source: Y. Hu, J. Gross, et al. "Finite Blocklength Performance of Multi-Terminal Wireless Industrial Networks", submitted