REAL TIME CONTROL IN 5G: Embedded Communication Networks -A System-Theoretic Modeling Approach

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Outline

- 1. Distributed Real-Time Applications
- Communication Networks as Embedded Systems in Distributed Networked Control Systems (NCS) -A System Theoretic Approach
- 3. Application Examples
 - 3.1 SDN- and NFV-Based Control of RT Packet Flow Switching
 - 3.2 Latencies for Error-Control Protocols
 - 3.3 E-E Latency in Core Packet Networks
- 4. Conclusions

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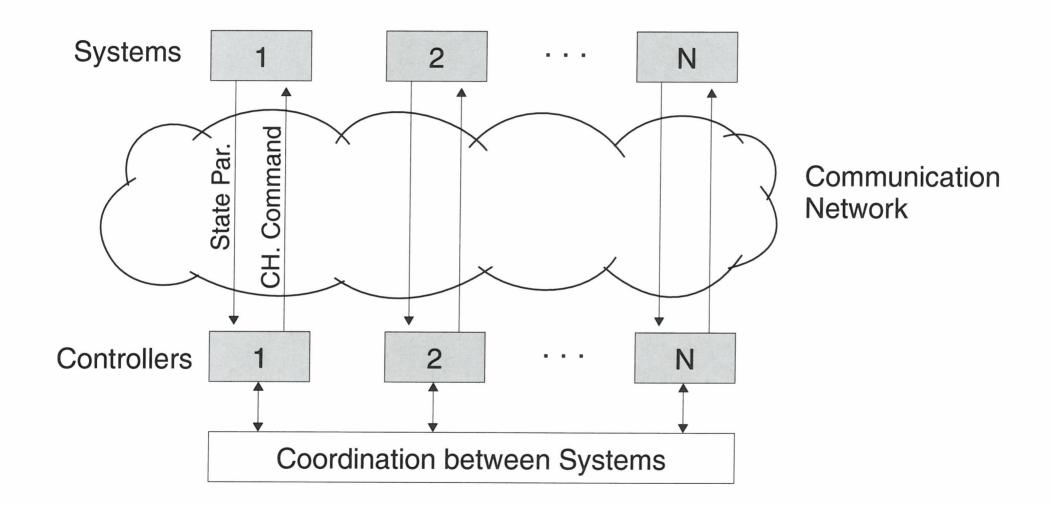
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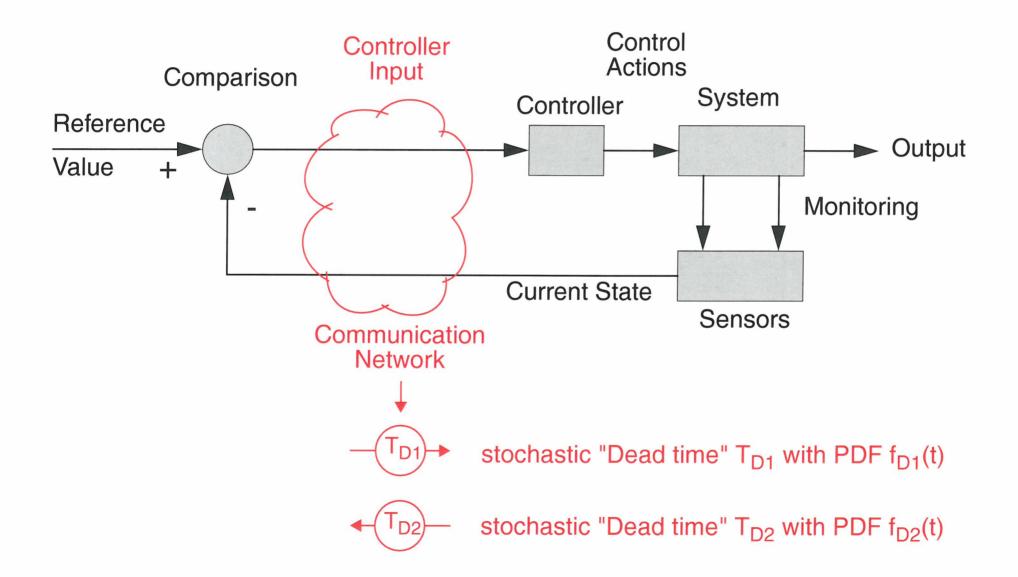
1. Distributed Real-Time Applications

- Distributed Electric Power Control in the "Smart Grid"
 - Feeding highly volatile el. Energy in the Power Grid
 - Feeding Control Based on Phasor Sensing Data
- Smart Traffic Control ("Smart City")
 - Intelligent Traffic Control
 - Accident / Desaster Management
- Integrated Industry Process ("Industry 4.0")
 - Production Automation
 - Integration in Enterprise Business Processes
- Human Health Surveillance
 - Sensoric Health Parameter Monitoring
 - Case Management

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Methodology: System Theoretic Approach

1. Modeling

- a) "Top Down" Approach from Application Contexts to Communication Networks
 - Identifying Interactions between Entities, e.g., Control Loops, Manufacturing Stations, ...
 - Identifying Communication Requirements between these Entities
 - Specifying Communication Network Requirements between Distantly Located Entities in Terms of: Throughput Rates, Latencies, etc. Quantitatively (Metrics)
- b) "Bottum-Up" Approach from Communication Networks to Applications
 - Identifying Available Communication Media (wired, wireless, electric, optic, ...)
 - Identifying Network Topologies and Network Technologies
 - Specifying Network Services, Architectures and Protocols
 Traffic and Performance Metrics
 Appropriate Communication Network Models

Methodology: System Theoretic Approach

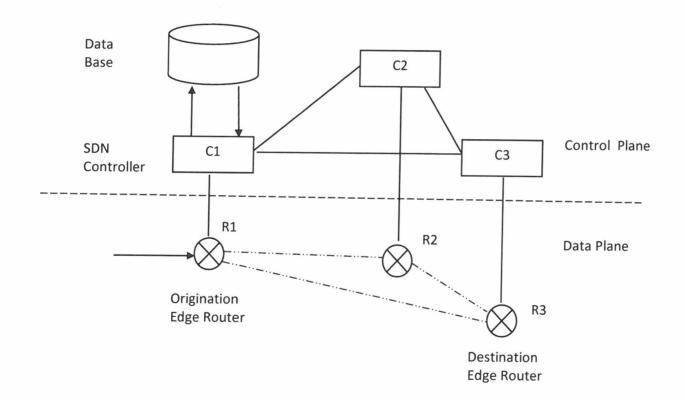
2. Performance Analysis

- a) Experimental Approach through Experiments, Measurements and Simulation
 - Design of a Physical Environment as Experimental Testbed
 - Executing Experiments and Performing Measurements
 - Development of System Simulation Models
 Running Simulations for Typical System Scenarios
 Extraction of Performance Results from Simulations
- b) Analytical Approach through Mathematical Performance Models
 - Identifying Existing/Approved Standard Queuing Models
 - Developing Complex Queuing Network Models
 Determination of the Main Application Requirements by Performance Metrics
 - Task Graph Representations and Task Graph Analysis by
 - Task Graph Reductions by Stepwise Aggregation of Tasks Probabilistically
 - Aggregation of Specific Models into higher Layer Models

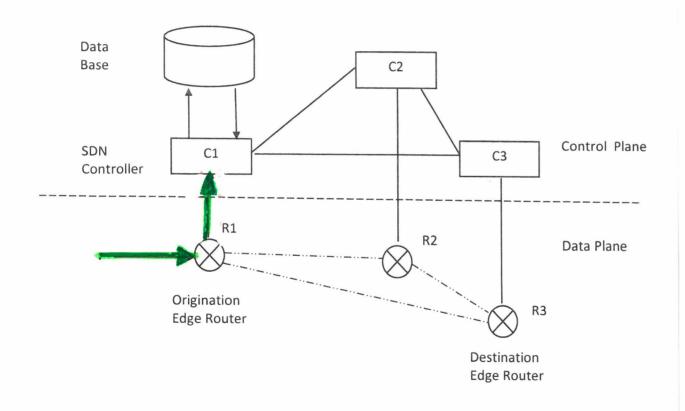
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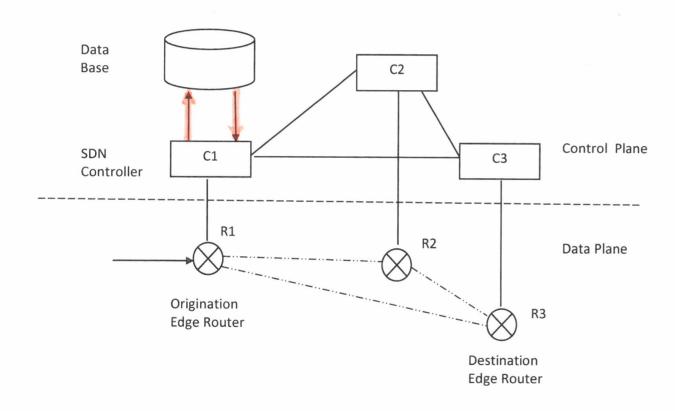
 SDN- and NFV-Based Control of Real-Time Packet Flow Switching Network Architecture



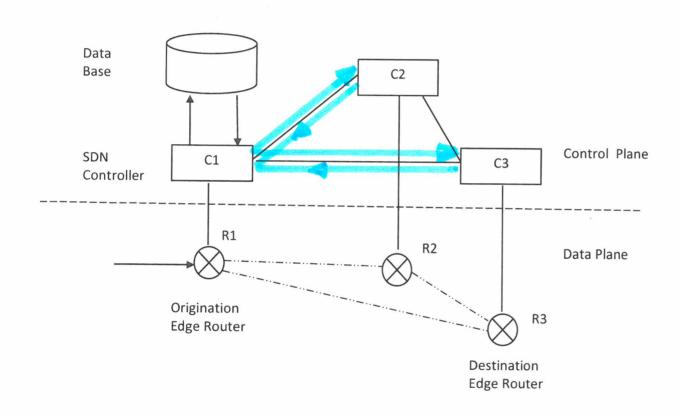
 SDN- and NFV-Based Control of Real-Time Packet Flow Switching Control Plane Actions and Data Plane MPLS Path Establishment



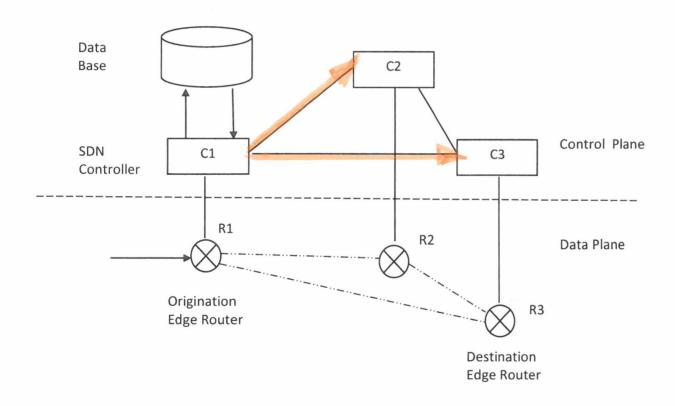
 Packet Arrival, Flow Detection



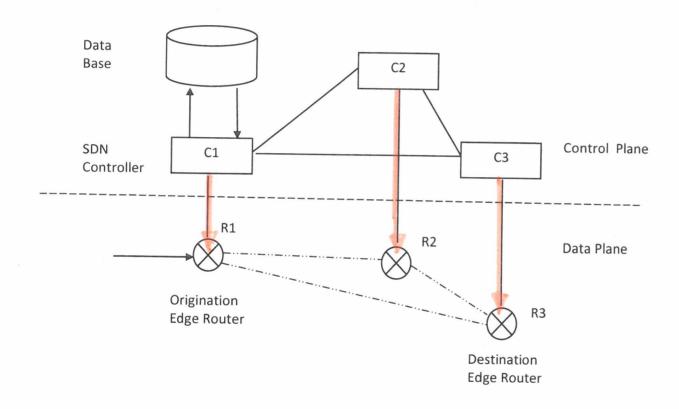
- Packet Arrival, Flow Detection
- 2. DB Inquiry



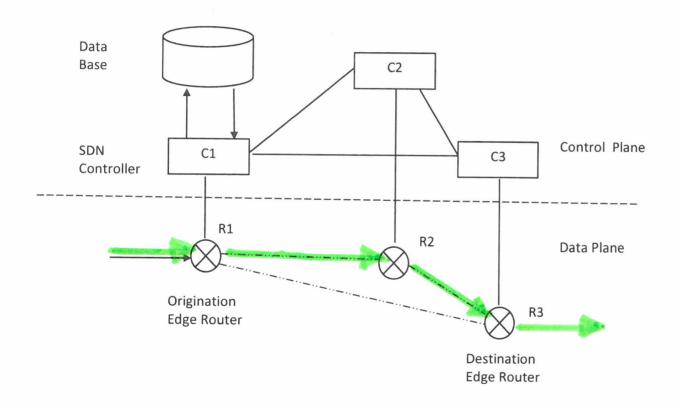
- Packet Arrival, Flow Detection
- 2. DB Inquiry
- 3. Controller Communication (Request)



- Packet Arrival, Flow Detection
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- Controller Communication (Command)

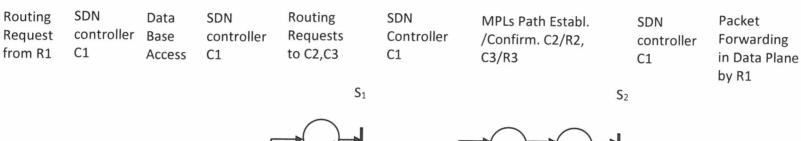


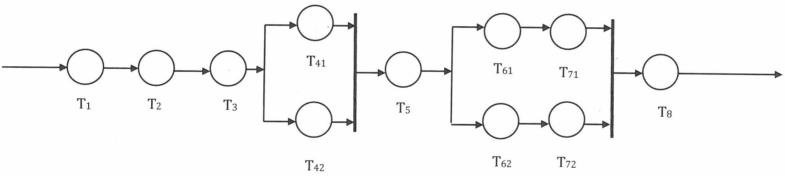
- Packet Arrival, Flow Detection
- 2. DB Inquiry
- 3. Controller Communication (Request)
- 4. Controller Communication (Command)
- 5. Label Path Information



- Packet Arrival, Flow Detection
- 2. DB Inquiry
- 3. Controller Communication (Request)
- 4. Controller Communication (Command)
- 5. Label Path Information
- Label Switched Packet Flow

 SDN- and NFV-Based Control of Real-Time Packet Flow Switching Control Plane Task Graph

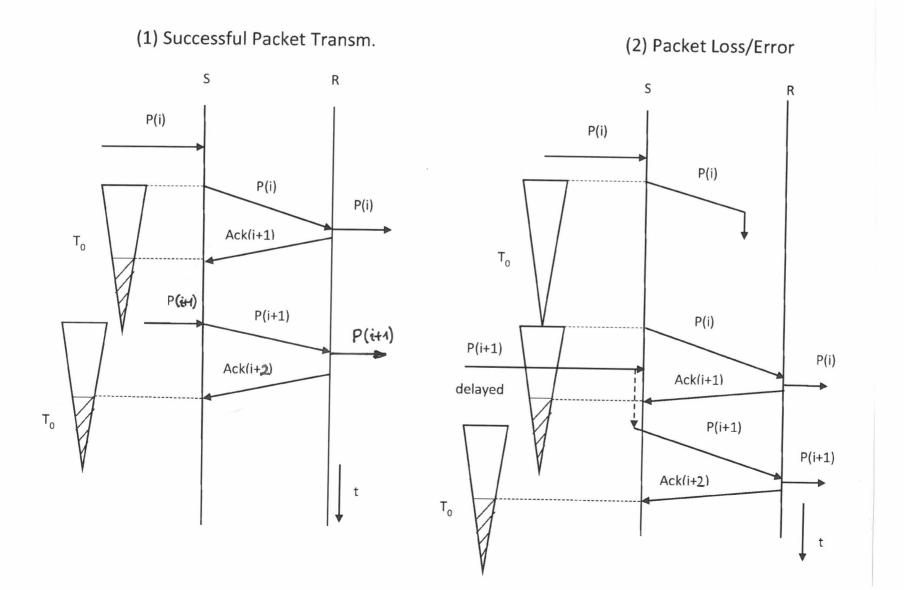




 S_1 , S_2 : Re-Synchronization Points (Maximum Operator) After parallel path

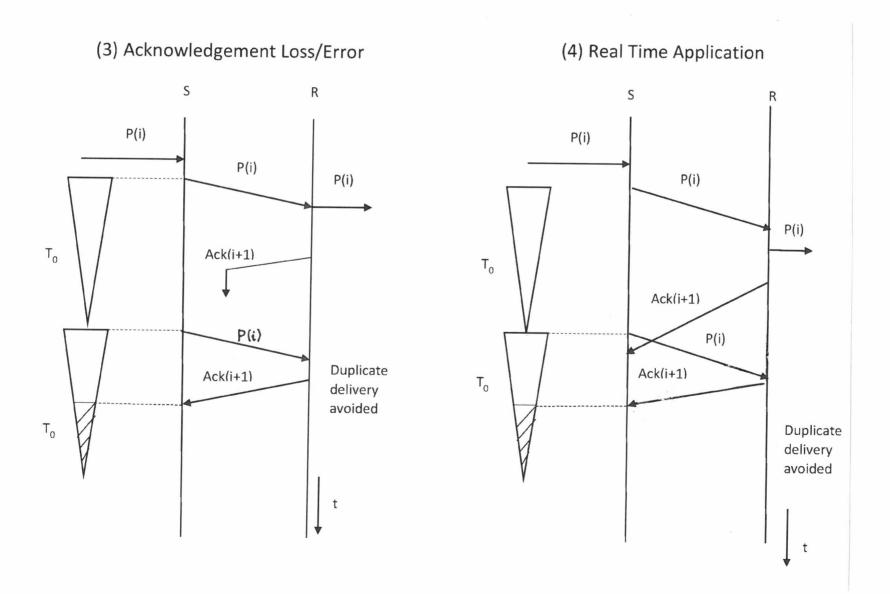
Modeling Protocol Control

Message Sequence Chart for "Send-and-Wait" Protocol with "Timeout Recovery"

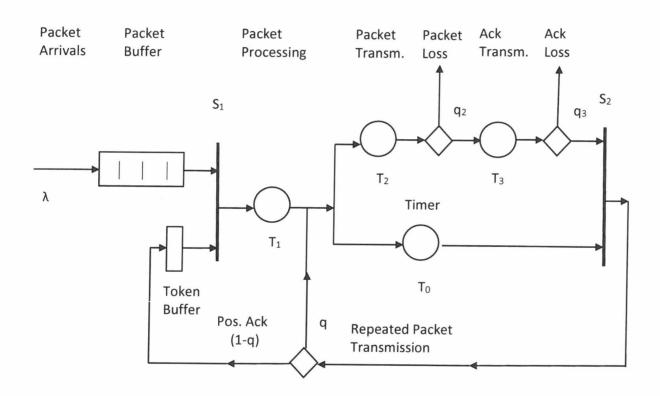


Modeling Protocol Control

Message Sequence Chart for "Send-and-Wait" Protocol with "Timeout Recovery"



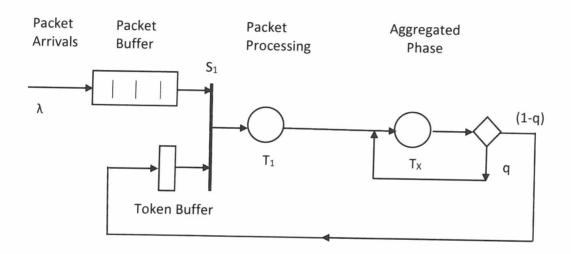
Task Graph of "Send-and-Wait" Protocol



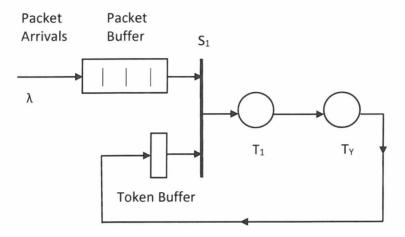
S1: Packet Admission Token Operator

S2: Minimum Path Duration Operator

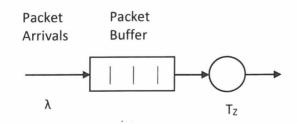
Task Graph Reduction Step 1: Aggregation of Parallel Execution paths by T_X



Task Graph Reduction Step 2: Aggregation of Repeated Packet Transmission by T_Y



Task Graph Reduction Step 3: Aggregation of Tasks T₁ and T_Y



Mathematical Operations for Task Graph Reduction: Steps 1 and 2

Step 1: Aggregation of the Serial phases T₂, T₃ by T_X (Two-Way Response Time)

$$T_X = T_2 + T_3$$
, T_2, T_3 are independent of each other : PDF $f_X(t) = f_2(t) \bigotimes f_3(t)$ \bigotimes Convolution Operator

Step 2: Number of Repeated Packet Transmissions

- a) Conditions for a Successful Packet and Ack Transmission
 - a1) Probability of correct Packet (P) and Acknowledgement (A) Transmission:

$$(1-q') = (1-q_2)(1-q_3)$$
, Where q_2 , q_3 are the probabilities of Packet, Ack. Loss, resp.

a2) Probability that two-way response time is within the Timeout range To

$$q_X = P\{ T_X \le T_0 \} = \int_{t=0}^{T_0} f_x(t) dt$$

b) Probability for a Repeated Packet Transmission q

$$(1-q) = (1-q') q_X, q = 1- (1-q_2) (1-q_3) q_X$$

c) Number of Repeated Packet Transmissions until a Successful Packet Communication

$$q_n = P\{n \text{ Repeated Packet Transm.}\} = q^n(1-q), n=0,1,2,... (Geometric Distribution)$$

Mathematical Operations for Task Graph Reduction: Steps 3, 4 and 5

Step 3: Aggregation of all Packet Transmissions until completion of a Successful Packet Transmission

where $\delta(t)$ the Delta-Function (Dirac impulse), u(t) the unit step function.

Step 4: Aggregation of Packet Processing Time T₁ and Aggregated Packet Transmission Time T_v

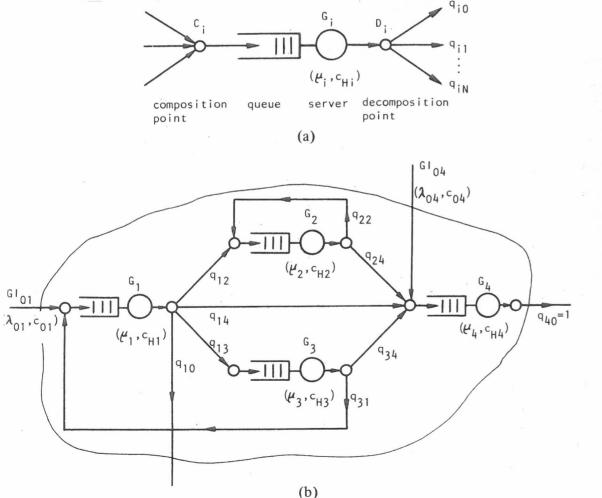
$$f_z(t) = f_1(t) \bigotimes f_Y(t)$$

Step 5: Resulting Single-Server Queuing System GI/G/1

After Aggregation of T₁ and T_Y by T_Z the Feedback Model is Identical with a GI/G/1 FIFO Queuing System.

Modeling the Core Network by a General Queuing Network

- (a) One Queuing Station
- (b) Example Queuing Network



Arrival and Service Processes

 $GI_0 = (GI_{0i})$ Vector of exogenous arrival processes. $\lambda_0 = (\lambda_{0i})$ Vector of exogenous arrival rates, where

 $a_{0i} = 1/\lambda_{0i}$ is the mean exogenous interar-

rival time at station i.

 $c_0 = (c_{0i})$ Vector of the coefficients of variation of

the exogenous arrival processes.

 $G = (G_i)$ Vector of service processes.

 $\mu = (\mu_i)$ Vector of service rates, where $h_i = 1/\mu_i$ is

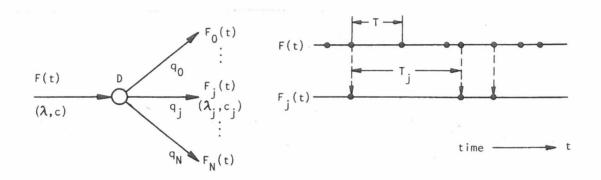
the mean service time at station i.

 $c_H = (c_{Hi})$ Vector of the coefficients of variation of

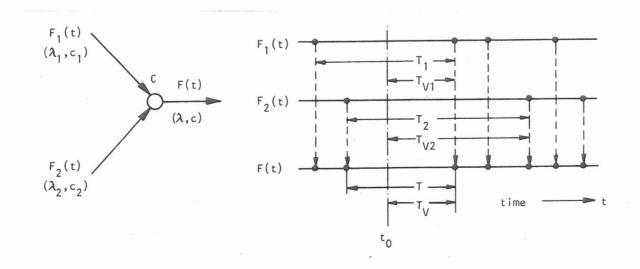
the service processes.

Basic Operations

- (a) Packet Traffic Rates at each Queuing Station
 Solution of a linear System of Equations ("Conservation of Flows")
- (b) Splitting of Packet Streams ("Probabilistic Routing")

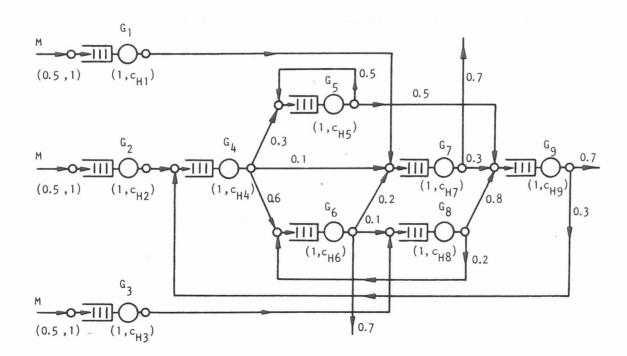


(c) Superposition of Packet Streams (Renewal Process Assumption)



Numerical Example

Queuing Network with 9 Queuing Stations

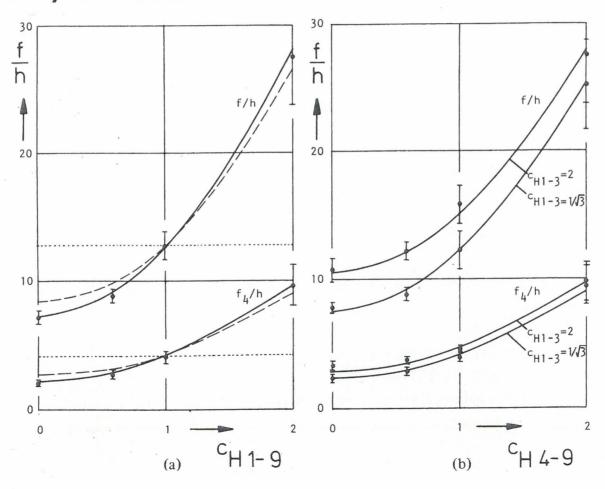


Numerical Example

Results for Total E - E Average Flow Time f and Station Flow Time f₄

Dependent on Coefficient of Variation cH of Station Service Times

and Validation by Simulations



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- Future Application Fields as Power/Traffic Grids or Integrated Manufacturing Systems lead to Distributed and Highly Complex Systems with High Requirements to Communications and Real-Time Performance ("Tactile Internet")
- Challenges Require Cooperative Approaches between Experts/Methodologies of Different Competences
- Complexity has to be Reduced by Structured Approaches as step-wise Top-Down, Bottom-Up, Decomposition/Aggregation Methods where Existing or Approved Results can be Applied
- Several Examples have been Presented for the Demonstration of the Feasibility of the Proposed Methodology